ENGR 1AR Introduction to Engineering Design: Autonomous Rover Summer Schedule

Monday-Friday 9:00 am - 4:00 pm Location: Mathematical Science 2915

Instructor of Record: Prof. Jacob Schmidt, Ph.D., <u>schmidt@seas.ucla.edu</u>

Tentative Course Outline and Schedule:

Week	Date	Торіс	Assignments (tentative)
1	6/26	 Class Introduction Introduction of mentors and course expectations Electronics Lecture Computer-aided design in Solidworks Fun CAD Design Practice 	Complete Pre-Class survey Download softwares assigned TinkerCad Assignment
		Intro to PCB Design Schematics drawing and pcb layout using Kicad Soldering and Vinyl Cutting Workshop	PCB Assignment Soldering Project Form Groups
		 Arduino Coding In depth coding including logic structures Activity wiring up servos and H-bridges Introduction to Bluetooth Model Rover Assembling Combine previous work and assemble a drivable dummy rover 	Wiring/Programming Projects Model Rover Assemble
		Solidworks Lecture - Makerspace tour - CAD, assembly, lasercut Model Rover design - Design own layout of model rover	Lasercut and 3d-print Assignment CAD design for Model Rover
		Scavenger Hunt	
2	7/3 - 7/7	Model Rover Test Drive Team Presentation	Model Rover Full assemble
		 Introduction to Autonomy Progress from manual navigation to autonomous Introduction to Mechanical Design Team Brainstorm 	

		Presentation Workshop Team Design	
		Preliminary Design Review (PDR)	PDR Presentation
		Rover Manufacture	
3	7/10 - 7/14	 Rover Manufacture Rover must be able to move, using sensors Testing and adjustments to build and program Grabbing mechanism should be working Testing and adjustments to build and program 	
		Obstacle Course Practice Test Drive	Finish Rovers
		Final Project Competition Reflective Presentation	Final Competition

• Course attendance is *extremely important*.